DISCRETIZATION OF A MATHEMATICAL MODEL FOR TUMOR-IMMUNE SYSTEM INTERACTION WITH PIECEWISE CONSTANT ARGUMENTS

Senol Kartal¹ and Fuat Gurcan²

¹Department of Mathematics, Nevsehir Hacı Bektas Veli University, Nevsehir, Turkey ²Department of Mathematics, Erciyes University, Kayseri, Turkey ²Faculty of Engineering and Natural Sciences, International University of Sarajevo, Hrasnicka cesta 15, 71000, Sarejevo, BIH

ABSTRACT

The present study deals with the analysis of a Lotka-Volterra model describing competition between tumor and immune cells. The model consists of differential equations with piecewise constant arguments and based on metamodel constructed by Stepanova. Using the method of reduction to discrete equations, it is obtained a system of difference equations from the system of differential equations. In order to get local and global stability conditions of the positive equilibrium point of the system, we use Schur-Cohn criterion and Lyapunov function that is constructed. Moreover, it is shown that periodic solutions occur as a consequence of Neimark-Sacker bifurcation.

KEYWORDS

piecewise constant arguments; difference equation; stability; bifurcation

1. Introduction

In population dynamics, the simplest and most widely used model describing the competition of two species is of the Lotka-Volterra type. In addition, there exist numerous extensions and generalizations of this type model in tumor growth model [1-8]. In 1995, Gatenby [1] used Lotka-Volterra competition model describing competition between tumor cells and normal cells for space and other resources in an arbitrarily small volume of tissue within an organ. On the other hand, Onofrio [2] has presented a general class of

Lotka-Volterra competition model as follows:

$$\begin{cases} x' = x(f(x) - \phi(x)y), \\ y' = \beta(x)y - \mu(x)y + \sigma q(x) + \theta(t). \end{cases}$$
 (1)

Here x and y denote tumor cell and effector cell sizes respectively. The function f(x) represents tumor growth rates and there are many versions of this term. For example, in Gompertz model: f(x) = Log(A/x) [3], the logistic model: f(x) = (1 - x/A) [4].

The metamodel (1) also includes following exponential model which has been constructed by Stepanova [6].

$$\begin{cases} x' = \mu_C x(t) - x(t)y(t), \\ y' = \mu_I (x(t) - x(t)^2)y(t) - y(t) + x(t) \end{cases}$$
 (2)

where X and y denote tumor and T-cell densities respectively. In this model, μ_C is the multiplication rate of tumors, is the rate of elimination of cancer cells by activity of T-cells, μ_I represents the production of T-cells which are stimulated by tumor cells, $^{-1}$ denotes the saturation density up from which the immunological system is suppressed, is the natural death rate of T cell and is the natural rate of influx of T cells from the primary organs [3].

Recently, it has been observed that the differential equations with piecewise constant arguments play an important role in modeling of biological problems. By using a first-order linear differential equation with piecewise constant arguments, Busenberg and Cooke [9] presented a model to investigate vertically transmitted. Following this work, using the method of reduction to discrete equations, many authors have analyzed various types of differential equations with piecewise constant arguments [10-19]. The local and global behavior of differential equation

$$\frac{dx(t)}{dt} = rx(t)\{1 - x(t) - i_0x([t]) - i_1x([t-1])\}$$
(3)

has been analyzed by Gurcan and Bozkurt [10]. Using the equation (3), Ozturk et al [11] have modeled a population density of a bacteria species in a microcosm. Stability and oscillatory characteristics of difference solutions of the equation

$$\frac{dx(t)}{dt} = x(t) \left\{ r \left(1 - \epsilon x(t) - \frac{1}{2} x([t]) - \frac{1}{2} x([t-1]) \right) + \gamma_1 x([t]) + \frac{1}{2} x([t-1]) \right\}$$
(4)

has been investigated in [12]. This equation has also been used for modeling an early brain tumor growth by Bozkurt [13].

In the present paper, we have modified model (2) by adding piecewise constant arguments such as

$$\begin{cases} x' = \mu_C x(t) - x(t)y([t]), \\ y' = \mu_I(x([t]) - x([t])^2)y(t) - y(t) + \zeta \end{cases}$$
 (5)

where [t] denotes the integer part of $t \in [0,]$ and all these parameters are positive.

2. STABILITY ANALYSIS

In this section, we investigate local and global stability behavior of the system (5). The system can be written in the interval $t \in [n, n + 1)$ as

$$\begin{cases} \frac{dx}{x(t)} = \left(\mu_C - y(n)\right) d(t), \\ \frac{dy}{dt} + \left(\beta \mu_I x(n)^2 + -\mu_I x(n)\right) y(t) = . \end{cases}$$
(6)

Integrating each equations of system (6) with respect to t on [n, t) and letting t = n + 1, one can obtain a system of difference equations

$$\begin{cases} x(n+1) = x(n)e^{\mu_C - y(n)}, \\ y(n+1) = \frac{e^{\left[\mu_I x(n) - |\mu_I x(n)^2 - i\right]} \left[\beta \mu_I x(n)^2 y(n) + y(n) - \mu_I x(n) y(n) - i\right] + \kappa}{\mu_I x(n)^2 + -\mu_I x(n)}.$$
 (7)

Computations give us that the positive equilibrium point of the system is

$$(\bar{x},\bar{y}) = \begin{pmatrix} 1 - \frac{1}{4} & + (-4\beta \delta + \mu_I)\mu_C \\ \frac{\sqrt{\mu_I}\sqrt{\mu_C}}{2} & \mu_C \end{pmatrix}.$$

Hereafter,

$$<\frac{\mu_C}{}$$
 and $\frac{\mu_I\mu_C}{-4 + 4 \mu_C}$. (8)

The linearized system of (7) about the positive equilibrium point is w(n + 1) = Aw(n), where A is a matrix as;

$$A = \begin{pmatrix} 1 & \frac{1}{\sqrt{4 + (-4 + \mu_{I})\mu_{C}}} \\ \frac{e^{-\mu_{C}}(-1 + e^{\mu_{C}})\sqrt{\mu_{I}}\mu_{C}^{3/2}\sqrt{4 + (-4 + \mu_{I})\mu_{C}}} \\ \frac{e^{-\mu_{C}}(-1 + e^{\mu_{C}})\sqrt{\mu_{C}}\mu_{C}^{3/2}}}{\mu_{C}}$$

The characteristic equation of the matrix A is

$$p(\) = \ ^2 + \ \left(-1 - e^{-\mu_C} \right) + e^{-\mu_C} - \frac{e^{-\mu_C} (-1 + e^{\mu_C}) \mu_C \sqrt{4} + (-4 + \mu_I) \mu_C}{2} (-\sqrt{\mu_I} \sqrt{\mu_C} + \sqrt{4} + (-4 + \mu_I) \mu_C} \right). (10)$$

Now we can determine the stability conditions of system (7) with the characteristic equation (10). Hence, we use following theorem that is called Schur-Chon criterion.

Theorem A ([20]). The characteristic polynomial

$$p(\) = \ ^2 + p_1 + p_0 \tag{11}$$

has all its roots inside the unit open disk (| < 1) if and only if

(a)
$$p(1) = 1 + p_1 + p_0 > 0$$
,
(b) $p(-1) = 1 - p_1 + p_0 > 0$,

(c)
$$D_1^+ = 1 + p_0 > 0$$
,
(d) $D_1^- = 1 - p_0 > 0$.

Theorem 1. The positive equilibrium point (\bar{x}, \bar{y}) of system (7) is local asymptotically stable if $\frac{\mu_C^2}{+\mu_C} < \frac{\mu_C}{-4}$ and $\frac{\mu_I \mu_C}{-4 + 4 \mu_C}$.

Proof. From characteristic equations (10), we have

$$\begin{split} p_1 &= -1 - e^{-\overline{\mu_C}}, \\ p_0 &= e^{-\overline{\mu_C}} - \\ &= \underbrace{e^{-\overline{\mu_C}}(-1 + e^{\overline{\mu_C}})\mu_C\sqrt{4} + (-4 + \mu_I)\mu_C}_{2}(-\sqrt{\mu_I}\sqrt{\mu_C} + \sqrt{4} + (-4 + \mu_I)\mu_C}) \end{split}$$

From Theorem A/a we get

$$p(1) = \frac{2 - (-1 + e^{\overline{\mu_C}})\mu_C\sqrt{4} + (-4 + \mu_I)\mu_C}{2} (-\sqrt{\mu_I}\sqrt{\mu_C} + \sqrt{4} + (-4 + \mu_I)\mu_C})$$

It can be shown that if

$$-\sqrt{\mu_{\rm I}}\sqrt{\mu_{\rm C}} + \sqrt{4 + (-4 + \mu_{\rm I})\mu_{\rm C}} < 0, \tag{12}$$

then p(1) > 0. On the other hand, the inequality (12) always holds under the condition (8). When we consider Theorem A/b and Theorem A/c with the fact (12), we have respectively

$$p(-1) = 2 + 2e^{-\frac{1}{\mu_C}}$$

$$-\frac{e^{-\frac{1}{\mu_C}(-1 + e^{\frac{1}{\mu_C}})\mu_C\sqrt{4} + (-4 + \mu_I)\mu_C}(-\sqrt{\mu_I}\sqrt{\mu_C} + \sqrt{4 + (-4 + \mu_I)\mu_C})}{2} > 0$$
And

$$\begin{split} D_1^+ &= 1 + e^{-\mu_C} - \\ &= \frac{e^{-\mu_C} (-1 + e^{\mu_C}) \mu_C \sqrt{4} + (-4 + \mu_I) \mu_C}{2} (-\sqrt{\mu_I} \sqrt{\mu_C} + \sqrt{4} + (-4 + \mu_I) \mu_C}) > 0. \end{split}$$

From Theorem A/d, we get

$$D_1^- = e^{-\overline{\mu}_C} (-1 + e^{\overline{\mu}_C}) (2 \\ + 4 \\ \mu_C + (-4 \\ + \mu_I) \mu_C^2 - \sqrt{\mu_I} \mu_C^{\frac{3}{2}} \sqrt{4 \\ + (-4\beta \xi + \mu_I) \mu_C}).$$

By using the conditions of Theorem 1, we can also see that $D_1^- > 0$. This completes the proof.

Now we can use parameters value in Table 1 for the testing the conditions of Theorem 1. Using these parameter values, it is observed that the positive equilibrium

point $(\bar{x}, \bar{y}) = (7.41019, 0.5599)$ is local asymptotically stable where blue and red graphs represent x(n) and y(n) population densities respectively (see Figure 1).

Parameters	Numerical Values	Ref
μ _C tumor growth parameter	0.5549	[8]
interaction rate	1	[8]
μ _I tumor stimulated proliferation rate	0.00484	[8]
inverse threshold for tumor suppression	0.00264	[8]
death rate	0.37451	[8]
rate of influx	0.19	

Table 1. Parameters values used for numerical analysis

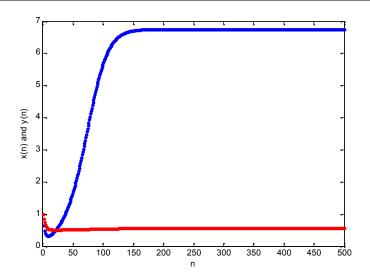


Figure 1. Graph of the iteration solution of x(n) and y(n), where x(1) = y(1) = 1

Theorem 2. Let $\{x(n),y(n)\}_{n=-1}$ be a positive solution of the system. Suppose that $\mu_C-y(n)<0$, x(n)-1>0 and $\mu_Ix(n)^2y(n)+y(n)-\mu_Ix(n)y(n)-<0$ for n=0,1,2,3... Then every solution of (7) is bounded, that is,

$$x(n)$$
 (0, $x(0)$) and $y(n)$ (0, -).

Proof. Since $\{x(n), y(n)\}_{n=-1} > 0$ and $\mu_C - y(n) < 0$, we have

$$x(n + 1) = x(n)e^{\mu}c^{-y(n)} < x(n).$$

In addition, if we use $\mu_I x(n)^2 y(n) + y(n) - \mu_I x(n) y(n) - < 0$ and x(n) - 1 > 0, we have

$$y(n+1) = \frac{e^{\left[\mu_I x(n) - |\, \mu_I x(n)^2 - i\right]} \big[y(n) (\ \mu_{\underline{I}} x(n)^2 + \ - \mu_{\underline{I}} x(n)) - \ :\big] + \kappa}{\mu_I x(n) (\ x(n) - 1) +}$$

$$<\frac{1}{\mu_1 x(n)(x(n)-1)+1}<-.$$

This completes the proof.

Theorem 3. Let the conditions of Theorem 1 hold and assume that

then the positive equilibrium point of the system is global asymptotically stable.

Proof. Let $\overline{E} = (\overline{x}, \overline{y})$ is a positive equilibrium point of system (7) and we consider a Lyapunov function V(n) defined by

$$V(n) = [E(n) - \overline{E}]^2, n = 0,1,2...$$

The change along the solutions of the system is

$$V(n) = V(n+1) - V(n) = \{E(n+1) - E(n)\}\{E(n+1) + E(n) - 2\overline{E}\}.$$

Let $A_1 = \mu_C - y(n) < 0$ which gives us that $y(n) > \frac{\mu_C}{n} = \bar{y}$. If we consider first equation in (7) with the fact $x(n) > 2\bar{x}$, we get

$$\begin{split} V_1(n) &= \{x(n+1) - x(n)\}\{x(n+1) + x(n) - 2\bar{x}\} \\ &= \big\{x(n)\big(e^{A_1} - 1\big)\big\}\{x(n)e^{A_1} + x(n) - 2\bar{x}\} < 0. \end{split}$$

Similarly, Suppose that $A_2 = \mu_I x(n)^2 + -\mu_I x(n) > 0$ which yields $x(n) > \frac{1}{2}$. Computations give us that if $y(n) > \frac{1}{A_2}$ and $y(n) > 2\bar{y}$, we have

$$\begin{split} V_2(n) &= \{y(n+1) - y(n)\}\{y(n+1) + y(n) - 2\overline{y}\} \\ &= \Big\{ \frac{\left(1 - e^{-A_2}\right)(\kappa - y(n)A_2)}{A_2} \Big\} \Big\} \frac{y(n)A_2\left(e^{-A_2} + 1\right) + \kappa\left(1 - e^{-A_2}\right) - 2\overline{y}A_2}{A_2} \Big\} < 0. \end{split}$$

Under the conditions

$$\bar{x} < \frac{1}{2^n} \text{ and } \bar{y} < \frac{1}{2\mu_I x(n)(x(n) - 1) + 2}$$

we can write

$$x(n) > \frac{1}{-} > 2\overline{x} \text{ and } y(n) > \frac{1}{A_2} = \frac{1}{\mu_I x(n)(x(n) - 1) + 1} > 2\overline{y}.$$

As a result, we obtain $V(n) = (V_1(n), V_2(n)) < 0$.

3. NEIMARK-SACKER BIFURCATION ANALYSIS

In this section, we discuss the periodic solutions of the system through Neimark-Sacker bifurcation. This bifurcation occurs of a closed invariant curve from a equilibrium point in discrete dynamical systems, when the equilibrium point changes stability via a pair of complex eigenvalues with unit modulus. These complex eigenvalues lead to periodic solution as a result of limit cycle. In order to study Neimark-Sacker bifurcation we use the following theorem that is called Schur-Cohn criterion.

Theorem B. ([20]) A pair of complex conjugate roots of equation (11) lie on the unit circle and the other roots of equation (11) all lie inside the unit circle if and only if

- (a) $p(1) = 1 + p_1 + p_0 > 0$,
- (b) $p(-1) = 1 p_1 + p_0 > 0$
- (c) $D_1^+ = 1 + p_0 > 0$, (d) $D_1^- = 1 p_0 = 0$.

In stability analysis, we have shown that Theorem B/a, Theorem B/b and Theorem B/c always holds. Therefore, to determine bifurcation point we can only analyze Theorem B/d. Solving equation d of Theorem B, we have $\bar{\kappa} = 0.0635352$. Furthermore, Figure 2 shows that $\bar{\kappa}$ is the Neimark-Sacker bifurcation point of the system with eigenvalues $|\lambda_{1,2}| = |0.945907 \pm 0.324439i| = 1$, where blue, and red graphs represent x(n) and y(n) population densities respectively.

As seen in Figure 2, a stable limit cycle occurs around the positive equilibrium point at the Neimark-Sacker bifurcation point. This limit cycle leads to periodic solution which means that tumor and immune cell undergo oscillations (Figure 3). This oscillatory behavior has also occurred in continuous biological model as a result of Hopf bifurcation and has observed clinically.

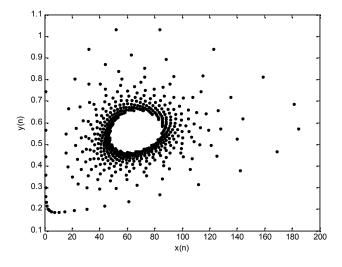


Figure 2. Graph of Neimark-Sacker bifurcation of system (7) for $\bar{\kappa} = 0.0635352$. Initial conditions and other parameters are the same as Figure 1

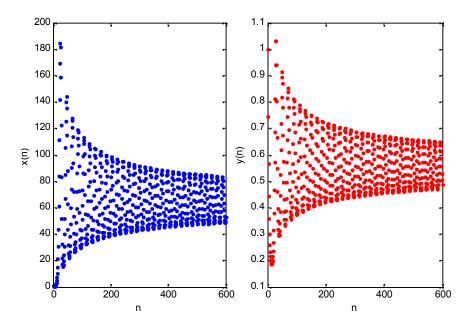


Figure 3. Graph of the iteration solution of x(n) and y(n) for $\bar{\kappa} = 0.063535$. Initial conditions and other parameters are the same as Figure 1

REFERENCES

- [1] Robert, A.Gatenby, (1995) "Models of tumor-host interaction as competing populations: implications for tumor biology and treatment", Journal of Theoretical Biology, Vol. 176, No. 4, pp447-455.
- [2] Alberto, D.Onofrio, (2005) "A general framework for modeling tumor-immune system competition and immunotherapy: mathematical analysis and biomedical inferences", Physica D-Nonlinear Phenomena, Vol. 208, No. 3-4, pp220-235.
- [3] Harold, P.de.Vladar & Jorge, A.Gonzales, (2004) "Dynamic respons of cancer under theinuence of immunological activity and therapy", Journal of Theoretical Biology, Vol. 227, No. 3, pp335-348.
- [4] Robert, A.Gatenby, (1995) "Models of tumor-host interaction as competing populations: implications for tumor biology and treatment", Journal of Theoretical Biology, Vol. 176, No. 4, pp447-455.
- [5] Vladimir, A.Kuznetsov, Iliya A.Makalkin, Mark A.Taylor & Alan S.Perelson (1994) "Nonlinear dynamics of immunogenic tumors: parameter estimation and global bifurcation analysis", Bulletin of Mathematical Biology, Vol. 56, No. 2, pp295-321.
- [6] N.V, Stepanova, (1980) "Course of the immune reaction during the development of a malignant tumour", Biophysics, Vol. 24, No. 5, pp917-923.
- [7] Alberto, D.Onofrio, (2008) "Metamodeling tumor-immune system interaction, tumor evasion and immunotherapy", Mathematical and Computer Modelling, Vol. 47, No. 5-6, pp614-637.
- [8] Alberto, D.Onofrio, Urszula, Ledzewicz & Heinz, Schattler (2012) "On the Dynamics of Tumor Immune System Interactions and Combined Chemo- and Immunotherapy", SIMAI Springer Series, Vol. 1, pp249-266.
- [9] S. Busenberg, & K.L. Cooke, (1982) "Models of vertically transmitted diseases with sequential continuous dynamics", Nonlinear Phenomena in Mathematical Sciences, Academic Press, New York, pp.179-187.
- [10] Fuat, Gürcan, & Fatma, Bozkurt (2009) "Global stability in a population model with piecewise constant arguments", Journal of Mathematical Analysis And Applications, Vol. 360, No. 1, pp334-342.
- [11] Ilhan, Öztürk, Fatma, Bozkurt & Fuat, Gürcan (2012) "Stability analysis of a mathematical modelin a microcosm with piecewise constant arguments", Mathematical Bioscience, Vol. 240, No. 2, pp85-91.

- [12] Ilhan, Öztürk & Fatma, Bozkurt (2011) "Stability analysis of a population model with piecewise constant arguments", Nonlinear Analysis-Real World Applications, Vol. 12, No. 3, pp1532-1545.
- [13] Fatma, Bozkurt (2013) "Modeling a tumor growth with piecewise constant arguments", Discrete Dynamics Nature and Society, Vol. 2013, Article ID 841764 (2013).
- [14] Kondalsamy, Gopalsamy & Pingzhou, Liu (1998) "Persistence and global stability in a populationmodel", Journal of Mathematical Analysis And Applications, Vol. 224, No. 1, pp59-80.
- [15] Pingzhou, Liu & Kondalsamy, Gopalsamy (1999) "Global stability and chaos in a population model with piecewise constant arguments", Applied Mathematics and Computation, Vol. 101, No. 1, pp63-68
- [16] Yoshiaki, Muroya (2008) "New contractivity condition in a population model with piecewise constant arguments", Journal of Mathematical Analysis And Applications, Vol. 346, No. 1, pp65-81.
- [17] Kazuya, Uesugi, Yoshiaki, Muroya & Emiko, Ishiwata (2004) "On the global attractivity for a logistic equation with piecewise constant arguments", Journal of Mathematical Analysis And Applications, Vol. 294, No. 2, pp560-580.
- [18] J.W.H, So & J.S. Yu (1995) "Persistence contractivity and global stability in a logistic equation with piecewise constant delays", Journal of Mathematical Analysis And Applications, Vol. 270, No. 2, pp602-635.
- [19] Yoshiaki, Muroya (2002) "Global stability in a logistic equation with piecewise constant arguments", Hokkaido Mathematical Journal, Vol. 24, No. 2, pp91-108.
- [20] Xiaoliang, Li, Chenqi, Mou, Wei, Niu & Dongming, Wang (2011) "Stability analysis for discrete biological models using algebraic methods", Mathematics in Computer Science, Vol. 5, No. 3, pp247-262.

Authors

Senol Kartal is research assistant in Nevsehir Haci Bektas Veli University in Turkey. He is a Phd student Department of Mathematics, University of Erciyes. His research interests include issues related to dynamical systems in biology.



Fuat Gurcan received her PhD in Accounting at the University of Leeds, UK. He is a Lecturer at the Department of Mathematics, University of Erciyes and International University of Sarajevo. Her research interests are related to Bifurcation Theory, Fluid Dynamics, Mathematical Biology, Computational Fluid Dynamics, Difference Equations and Their Bifurcations. He has published research papers at national and international journals.

